





## High Performance Dynamic Traffic Assignment Based on Variational Inequality



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## Outline

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- Dynamic Traffic Assignment
- > Dynamic User Equilibrium

## 2. Algorithm

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- Dynamic Network Loading Based on ODE
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- Discretization LWR model







## What's Dynamic Traffic Assignment ?

Dynamic traffic assignment is aimed at allocating traffic flow to every path and making their travel time minimized over the time.

Dynamic traffic assignment belongs to traffic planning, it plays an important role in Intelligent Transportation System

Such as Route Guidance in Google map Heat Map in Baidu map









## Introduction

Dynamic traffic assignment is the positive modeling of time-varying flows of automobiles on road network consistent with established traffic flow theory and travel demand theory.



Abstract Network

- Nodes: origin or destination
- Links : road
- Origin-Destination Pair
- Time cost = Delay = Travel Time







## Introduction

Continuous Time Dynamic User Equilibrium (DUE)

- Users choose the path with same and minimum travel time
  - Desired solution:
  - The departure rate function for each path
  - The corresponding cost function







Continuous Time Dynamic User Equilibrium (DUE)

For each individual, compared with your current travel cost:

If there is another path will lessen your travel cost, you switch!

If there is another departure time will lessen your travel cost, you switch!

◆ Facing with a new scenario, go back to the first two steps.

Until the Nash equilibrium is reached!







## Nash equilibrium

◆In game theory, the Nash equilibrium, named after American mathematician John Forbes Nash Jr₂, is a solution concept of a non-cooperative game involving two or more players in which each player is assumed to know the equilibrium strategies of the other players, and no player has anything to gain by changing only their own strategy.







# Solution? How's the transportation system going to look like under that equilibrium?

Fig Departure rates and corresponding travel cost in the DUE solution









## Solution?

 $\bullet$  To know the equilibrium strategies of the other players:

Dynamic Network Loading: The problem of finding link activity when travel demand and departure rates (path flows) are known is commonly referred to as the dynamic network loading problem To find the equilibrium:

Differential Variational Inequality (dVI)







## Progress

## Part 1: Dynamic Network Loading(Friesz, 2011)

Link state equation

Medium equation (coming from Taylor expansion)

Initial conditions

$$\frac{dx_{a_1}^p(t)}{dt} = h_p(t) - g_{a_1}^p(t) \quad \forall p \in P$$

$$\frac{dx_{a_i}^p(t)}{dt} = g_{a_{i-1}}^p(t) - g_{a_i}^p(t) \quad \forall p \in P, i \in [2, num(p)]$$

$$\frac{dg_{a_i}^p(t)}{dt} = r_{a_i}^p(t) \quad \forall p \in P, i \in [1, num(p)]$$

$$\frac{dr_{a_1}^p(t)}{dt} = R_{a_1}^p(x, g, r, h) \quad \forall p \in P$$

$$\frac{dr_{a_i}^p(t)}{dt} = R_{a_i}^p(x, g, r) \quad \forall p \in P, i \in [2, num(p)]$$

$$x_{a_i}^p((\tau - 1) \cdot \Delta) = x_{a_i}^{p,0} \quad \forall p \in P, i \in [1, num(p)]$$

$$g_{a_i}^p((\tau - 1) \cdot \Delta) = 0 \quad \forall p \in P, i \in [1, num(p)]$$

$$r_p^p((\tau - 1) \cdot \Delta) = 0 \quad \forall p \in P, i \in [1, num(p)]$$



Flow Propagation















## Progress

## Part 2: Convert DUE to DVI

 $D \lor (\Psi, \Lambda, [t_0, t_f])$ : find  $h^* \in \Lambda_0$  such that

$$\begin{cases} \sum_{p \in P} \int_{t_0}^{t_f} \Psi_p(t, h^*)(h - h^*) dt \ge 0 \ \forall h \in \Lambda \\ \\ where \ \Lambda = h \ge 0 : \frac{dy_{ij}}{dt} = \sum_{p \in P_{ij}} h_p(t), y_{ij}(0) = 0, y_{ij}(t_f) = Q_{ij} \end{cases}$$









## Progress

### Part 3: Solve DVI by Fixed-Point Iteration

**Equal solution** 

$$h^* = P_A[h^* - \alpha \Psi_p(t, h^*)]$$

For each iteration step

$$\sum_{p \in P_{ij}} \int_{t_0}^{t_f} [h_p^k(t) - \alpha \Psi(t, h_p^k) + v_{ij}]_{+} = Q_{ij}$$

Update new departure rate

 $h_p^{k+1} = \left[h_p^k(t) - \alpha \Psi(t, h_p^k) + v_{ij}\right]_+$ 









## Example: Small graph



Fig. Small Network

double TA[2] = {75.0,50.0}; double Q[2] = {400,200};

Jam density Free flow speed Length (km) Arc (vehicles/km) (km/5min) 

//initializing arc info

std::vector< arc\_type > arc= {{0,800,6,4},{1,800,6,8},{2,800,8,4},{3,800,8,10},{4,1000,8,8},{5,600,6,10}};

//initializing path info

std::vector<od\_pair\_type> DATA\_SET ={{{arc[2],arc[5]},{arc[0],arc[5]},{arc[0],arc[1],arc[3],arc[4]},{arc[2],arc[3],arc[4]}};







## Example: Small graph

Printing the range of v for ea	ch od pair:	
14.807292,14.807347		
9.542000,9.545713		
for 0 th h, ND/NX is 0.000004	NX is 77217.074806 ND is	0.301055 Q is 386.794661
for 1 th h, ND/NX is nan 🛛 NX	is 0.000000 ND is 0.000000	Q is 0.000000
for 2 th h, ND/NX is nan 🛛 NX	is 0.000000 ND is 0.000000	Q is 0.000000
for 3 th h, ND/NX is 0.000010	NX is 454.750382 ND is 0	.004661 Q is 13.142970
for 4 th h, ND/NX is 0.000001	NX is 32669.432778 ND is	0.037689 Q is 199.743774
for 5 th h, ND/NX is nan 🛛 NX	is 0.000000 ND is 0.000000	Q is 0.000000







### Example: Path 1









## Example: Path 4

350										50
300										40
000										30
250										20
200 ——										10
										0
150 ——										-10
100										20
										-30
50										-40
0										-50
0	10	20	30	40	50	60	70	80	90	







## Example: Path 5









## **Bottleneck**

## If given a large network

Not fast enough!









## Using openMP to implement parallel computing

```
m_counter=0;
h counter=0:
for(int a=0;a<DATA_SET.size();a++)</pre>
                                                                                                                        #pragma omp parallel for
                                                                                                                        for(int i=0;i<m;i++)</pre>
  for(int b=0;b<DATA_SET[a].size();b++)</pre>
                                                                                                                          double total_x=0;
    for(int c=0;c<DATA_SET[a][b].size();c++)</pre>
                                                                                                                          double total_dx=0;
      double total_x=0;
                                                                                                                          std::vector<double> current_arc=DATA_SET[M_MAP[i][0]][M_MAP[i][1]][M_MAP[i][2]];
      double total_dx=0;
                                                                                                                          int arc_num=int(current_arc[0]);
      int arc_num=int(DATA_SET[a][b][c][0]);
                                                                                                                          for(int j=0;j<ARC_MAP[arc_num].size();j++)</pre>
      for(int i=0;i<ARC_MAP[arc_num].size();i++)</pre>
                                                                                                                            total x+=x[ARC_MAP[arc_num][i]];
        total_x+=x[ARC_MAP[arc_num][i]];
        total_dx+=dxdt[ARC_MAP[arc_num][i]];
                                                                                                                            total_dx+=dxdt[ARC_MAP[arc_num][j]];
      if(c==0)
                                                                                                                          if(M_MAP[i][2]==0)
        dxdt[m_counter+2*m]=R(total_x,total_dx,x[m_counter+m],x[m_counter+2*m],
                                                                                                                            dxdt[i+2*m]=R(total_x,total_dx,x[i+m],x[i+2*m],
           h_spline[h_counter](t),DATA_SET[a][b][c]);
                                                                                                                              h_spline[INDEX_MAP[M_MAP[i][0]][M_MAP[i][1]]](t),current_arc);
        h_counter++;
                                                                                                                          }else{
      }else{
        dxdt[m_counter+2*m]=R(total_x,total_dx,x[m_counter+m],x[m_counter+2*m],
                                                                                                                            dxdt[i+2*m]=R(total_x,total_dx,x[i+m],x[i+2*m],
           x[m_counter+m-1],DATA_SET[a][b][c]);
                                                                                                                              x[i+m-1],current_arc);
      m_counter++;
```







## Using openMP to implement parallel computing

ODE calculationLinear search for v

◆12 cores, 24 threads







## Performance on small graph









#### Considering 10 OD pair and 30 paths

#### 

#### //initializing arc info

#### //initializing path info

std::vector<od\_pair\_type> DATA\_SET ={

- {{arc[2],arc[7],arc[37],arc[39],arc[75],arc[64]},{arc[2],arc[7],arc[36],arc[34],arc[41],arc[45],arc[59]}, {arc[2],arc[7],arc[36],arc[32],arc[29],arc[49],arc[53],arc[59]},{arc[1],arc[4],arc[16],arc[22],arc[49],arc[53],arc[59]}, {arc[3],arc[4],arc[16],arc[20],arc[18],arc[56]}},//5
- {{arc[4],arc[16],arc[22],arc[49],arc[53],arc[59]},{arc[4],arc[16],arc[20],arc[18],arc[56]},{arc[4],arc[16],arc[22],arc[55],arc[56]}},//3
- {{arc[10],arc[34],arc[42],arc[73],arc[75],arc[64]},{arc[10],arc[27],arc[30],arc[53],arc[59]},{arc[9],arc[12],arc[16],arc[22],arc[49],arc[53] {arc[9],arc[13],arc[25],arc[30],arc[53],arc[59]}},//4
- {{arc[13],arc[25],arc[28],arc[46],arc[69],arc[64]},{arc[12],arc[16],arc[22],arc[49],arc[53],arc[59]}},//2 {{arc[54],arc[56]},{arc[17],arc[22],arc[49],arc[53],arc[59]},{arc[18],arc[55],arc[49],arc[53],arc[59]}},//3
- {{arc[25],arc[28],arc[46],arc[69],arc[64]},{arc[25],arc[28],arc[46],arc[68]},{arc[24],arc[22],arc[49],arc[53],arc[59]}},//3
- {{arc[34],arc[42],arc[73],arc[75],arc[64]},{arc[32],arc[29],arc[49],arc[53],arc[59]},{arc[32],arc[28],arc[46],arc[68]}},//3
- {{arc[39],arc[75],arc[64]},{arc[39],arc[75],arc[69],arc[68]}},//2
- {{arc[46],arc[68]},{arc[46],arc[69],arc[64]},{arc[45],arc[59]}},//3
- {{arc[49],arc[53],arc[59]},{arc[50],arc[56]}}//2











#### Considering 10 OD pair and 30 paths

For	the	0 th	path,	the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	1 th	path,	the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	2 th	path,	the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	3 th	path,	the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	4 th	path,	the	integral	of	departure	rate	of	final	hk	is	399.945611
For	the	5 th	path,	the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6 <u>th</u>	path,	the	integral	of	departure	rate	of	final	hk	is	394.704573
For	the	7 th	path,	the	integral	of	departure	rate	of	final	hk	is	4.835398
For	the	8 th	path,	the	integral	of	departure	rate	of	final	hk	is	235.110113
For	the	9 <u>th</u>	path,	the	integral	of	departure	rate	of	final	hk	is	164.270061
For	the	10 <u>th</u>	path,	the	integral	l of	departure	: rate	e of	final	l <u>hk</u>	is	0.000000
For	the	11 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	l <u>hk</u>	is	0.000000
For	the	12 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	201.004450
For	the	13 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	198.743123
For	the	14 <u>th</u>	path,	the	integral	l of	departure	: rate	e of	final	l <u>hk</u>	is	399.917744
For	the	15 th	path,	the	integral	l of	departure	: rate	of	final	l <u>hk</u>	is	0.000000
For	the	16 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	0.000000
For	the	17 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	L <u>hk</u>	is	0.000000
For	the	18 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	L <u>hk</u>	is	400.014653
For	the	19 <u>th</u>	path,	the	integral	l of	departure	: rate	e of	final	l <u>hk</u>	is	0.000000
For	the	20 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	0.000000
For	the	21 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	L <u>hk</u>	is	0.000000
For	the	22 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	L <u>hk</u>	is	399.659963
For	the	23 <u>th</u>	path,	the	integral	l of	departure	: rate	e of	final	l <u>hk</u>	is	270.721623
For	the	24 th	path,	the	integral	l of	departure	: rate	of	final	l <u>hk</u>	is	128.991122
For	the	25 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	399.821417
For	the	26 <u>th</u>	path,	the	integral	l of	departure	: rate	e of	final	l <u>hk</u>	is	0.000000
For	the	27 th	path,	the	integral	l of	departure	: rate	: of	final	l hk	is	0.000000
For	the	28 th	path,	the	integral	l of	departure	: rate	of	final	l hk	is	0.000000
For	the	29 <u>th</u>	path,	the	integral	l of	departure	: rate	of	final	L <u>hk</u>	is	399.826259







## Sioux Falls Network :path no.30 Considering 10 OD pair and 30 paths





Fig. 1. Sioux Falls network.







#### Considering 10 OD pairs and 30 paths









#### Considering 23 OD pairs and 232 paths

17 17 17 18 18 18 18 18 18 18 18 18 18 18 18 18	19 21 25 55 55 55 55 55 55 55 55 56 56 56 56 56	14 23 25 47 48 48 48 49 61 61 62 62 63	3 11 27 19 26 27 27 51 57 57 57 65 66 67	8 31 14 23 23 31 33 27 43 43 67 43 43	5 5 8 311 12 8 31 33 26 27 438 27	5 8 14 5 9 35 23 23 23 27 35 33	5 5 3 12 5 11 8 31 6 35	14 8 5 8 9 5	3 5 5 12	14	3	
18	56	63	7	71	41	43	27	33	35	5		
17 17 17 17 18 18 18 18 18 18 18	19 19 21 21 55 55 55 55 55 55	14 15 23 25 47 47 48 48 48 48 48	11 11 12 27 19 21 26 26 27 27	8 8 14 31 23 23 23 31 33	5 5 8 11 11 12 8 35	1 5 8 8 14 5 5	1 5 5 1 1	1 1				









#### Considering 23 OD pairs and 232 paths

Path no.40:



For the 1 Kn path, the integral of departure rate of final hK is 0.00000 For the 3 Kh path, the integral of departure rate of final hK is 0.00000 For the 5 Kh path, the integral of departure rate of final hK is 0.00000 For the 5 Kh path, the integral of departure rate of final hK is 0.00000 For the 5 Kh path, the integral of departure rate of final hK is 0.00000 For the 7 Kh path, the integral of departure rate of final hK is 0.00000 For the 9 Kh path, the integral of departure rate of final hK is 0.00000 For the 9 Kh path, the integral of departure rate of final hK is 0.00000 For the 9 Kh path, the integral of departure rate of final hK is 0.00000 For the 11 Mh path, the integral of departure rate of final hK is 0.00000 For the 12 Mh path, the integral of departure rate of final hK is 0.00000 For the 13 Mh path, the integral of departure rate of final hK is 0.00000 For the 14 Mh path, the integral of departure rate of final hK is 0.00000 For the 15 Mh path, the integral of departure rate of final hK is 0.00000 For the 16 Mh path, the integral of departure rate of final hK is 0.00000 For the 16 Mh path, the integral of departure rate of final hK is 0.00000 For the 16 Mh path, the integral of departure rate of final hK is 0.00000 For the 18 Mh path, the integral of departure rate of final hK is 0.00000 For the 20 Mh path, the integral of departure rate of final hK is 0.00000 For the 21 Mh path, the integral of departure rate of final hK is 0.00000 For the 22 Mh path, the integral of departure rate of final hK is 0.00000 For the 23 Mh path, the integral of departure rate of final hK is 0.00000 For the 24 Mh path, the integral of departure rate of final hK is 0.00000 For the 25 Mh path, the integral of departure rate of final hK is 0.00000 For the 25 Mh path, the integral of departure rate of final hK is 0.00000 For the 25 Mh path, the integral of departure rate of final hK is 0.00000 For the 25 Mh path, the integral of departure rate of final hK is 0.000000 For the 35 Mh path, the integral of departure rate of fi	FOR	che		, n	pacit,	che	Integrat		ueparture	rate	٠ <u>.</u>	Tinat	- 41		20.0003/2	
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	FOR	cne	28	rü	path,	the	integra	1 01	ueparture	rate	OT	rinal	ΠK	15	20.008997	







#### Considering 23 OD pairs and 232 paths









## Table of average time for a single iteration









## With a larger graph, comes with a higher efficiency of openMP.







### Sioux Falls Network (Larger graph)

#### Considering 552 OD pair and 6255 paths

#### ♦ Iterations:12

- ◆ Running time: 10968.9 s
- $\blacklozenge$  Average time for a iteration: 914.1 s(15.2 min)
- Epsilon: 0.5

					-		•						
For	the	6208	th pat	th, the	integral	of	departure	rate	of	final	hk	is	5.628382
For	the	6209	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6210	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6211	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6212	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6213	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6214	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6215	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000
For	the	6216	th pat	th, the	integral	of	departure	rate	of	final	hk	is	4.373205
For	the	6217	th pat	th, the	integral	of	departure	rate	of	final	hk	is	0.000000







Sioux Falls Network (Larger graph) Considering 552 OD pair and 6255 paths Graph of path 6208

Graph of path 6216









## Future work

## Implementation on CUDA or GPU. Improvement on DNL based on DTA







#### Dynamic network loading by PDEs

LWR model --- hydrodynamic model

Non-linear PDE

$$\frac{\partial \rho(t, x)}{\partial t} + \frac{\partial f(\rho(t, x))}{\partial x} = 0$$

# Advantages Advantages Density-speed relationship First-in-First-out principle Route information

## It depends on the downstream and upstream flow state.



Water propagate in pipe

Thickness  $\rightarrow$  capacity

Water  $\rightarrow$  flow

Destination







### Implementation

#### Discretization (Han, 2012)

$$Da(t) = \begin{cases} q_{in}^{a}(t - \frac{L_{a}}{k_{a}}) & if N_{up}^{a}(t - \frac{L_{a}}{k_{a}}) = N_{down}^{a}(t) \\ C_{a} & if N_{up}^{a}(t - \frac{L_{a}}{k_{a}}) > N_{down}^{a}(t) \end{cases}$$

#### Link model

$$S_{a}(t) = \begin{cases} q_{out}^{a}(t - \frac{L_{a}}{w_{a}}) & if \, N_{up}^{a}(t) = N_{down}^{a}(t - \frac{L_{a}}{w_{a}}) + \rho_{jam}^{a}L_{a} & \text{Capacity} \\ C_{a} & if \, N_{up}^{a}(t) < N_{down}^{a}(t - \frac{L_{a}}{w_{a}}) + \rho_{jam}^{a}L_{a} & \text{Free} & \text{Congestion} \end{cases}$$



density







### Implementation

#### **Discretization** (Han, 2012)

#### Junction model

### Path delay

$$\alpha_{ij}^{J}(t) = \sum_{p \ni a,b} \mu_{a}^{p}(t, L_{a})$$
$$q_{out,i} = \min\{D_{i}(t), \frac{S_{j}(t)}{\alpha_{i}}\} j \in I^{o}$$
$$q_{in,j} = \sum_{i \in I^{v}} \alpha_{ij} \cdot q_{out,i}(t)$$

 $N_{down}^{a}(t) = N_{up}^{a}(\tau_{a}(t))$ 

 $travel_time = \tau_a(t) - t$ 



Moskowitz function

model by C **Initialization**: h0. (tolerance) path, timespan, Q(demand), epsilon arc, **for** all i = 1 : num (OD pair) While condition is true  $\blacktriangle$  hk - hk+1 is larger than tolerance **for** t =1 : num (timesteps) **for** i = 1 : num (links) **Solve D** Get link demand  $\triangleleft$  equation 5.2  $\triangleleft$  equation 5.3 **Solve S** Get link supply **for j** = 1 : num (linkin) **for** k = 1 : num (linkout) get turning ratio  $\triangleleft$  equation 5.4 end for end for end for Calculate entering flow  $\triangleleft$  equation 5.5 Calculate exiting flow  $\triangleleft$  equation 5.6 end for get effective path delay get a v in each iteration  $\triangleleft$  equation 3.3 update hk+1 according to equation 3.4  $\triangleleft$  each v map to a hk end while end for Output: Phi, hk



#### **Algorithm 2: Computing dynamic network loading based on LWR** Flow chart

et.







#### Discretization

The value in each cellular denotes the departure rate, downstream flow, upstream flow associate with different tables.

																			•		
		1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20
	1	0	0	0	0	0.2	0.3	0.4	0.5	0.6	0.7	0.5	0.2	0	0	0	0	0	0	0	0
	2	0	0	0	0	0.1	0.4	0.6	0.8	0.9	0.7	0.6	0.3	0	0	0	0	0	0	0	0
	3	0	0	0	0	0	0	0	0.6	0.2	0.3	0	0	0	0	0	0	0	0	0	0
	4	0	0	0	0	0	0	0.4	0.6	0.8	0.9	0.5	0.3	0	0	0	0	0	0	0	0
Į	5	0	0	0	0	0	0.6	0.7	0.7	0.6	0.5	0.2	0.4	0	0	0	0	0	0	0	0
(	6	0	0	0	0	0	0	0	0	0.3	0.4	0.5	0.6	0.4	0.3	0	0	0	0	0	0
-	7	0	0	0	0	0	0	0	0.2	0	0.4	0.5	0.6	0.5	0	0	0	0	0	0	0
8	8	0	0	0	0	0	0	0	0.6	0.6	0.7	0.5	0.4	0	0	0	0	0	0	0	0

Time Steps







### Link travel time example

Vertical difference  $\rightarrow$  length of link.

Slant line  $\rightarrow$  cumulative inflow and outflow

Horizontal difference  $\rightarrow$  link travel time









### Conclusion and remarks

For ODE model, > We apply *openMP* in solving *ODE* and fix-point iteration

- > succeed and obtain ideal assignment results.
- The parallel computing significantly fastened the solving speed as the same result compared with common computation
- In this way, it's possible to apply this technology to urban network planning.

For PDE model,  $\succ$  It remains many works to do. We haven't finish the entire code

- $\succ$  we proposed the pseudo code, and the next step is realizing it by C.
- If possible, parallel computing will be also used to certify the high performance in dynamic traffic assignment.







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**Programming Methods** 







## End

## Thank You